

Test Protocol

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DOCUMENT HISTORY

Version	Date	Changes made	Sign	Reviewer
0.1	2023-12-04	First draft.	All	ME
1.0	2023-12-05	First version.	EW	ME

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1 HEARING AIDS

1.1 Hardware

Test	Description	Pass/Fail	Date	Conclusion	Sign
1	Test if battery gives suffi- cient voltage over the cir-	Pass	2023-11-	Measured with multi meter	EW
	cuit.		21	1.4 V.	
2	Test if diode lits up.	Pass	2023-11-	LED on soundcard lights up	EW
		with note	21	as the hearing aids are pow-	
				ered. NOTE: LED only	
				lights up when sound is	
				present. Also soundcard	
				must be connected to com-	
				puter for LED to be lit.	

1.2 Sound source tracking

Test	Description	Pass/Fail	Date	Conclusion	Sign
3	Test the automatic speech	Pass	2023-11-	The ASR got activated af-	AR,
	recognition (ASR).		29	ter around 1 second when	RO
				switching from white noise	
				to human speech.	
4	Test the localization of the	Not exe-		Not tested.	
	direction and position esti-	cuted.			
	mate of a stationary sound				
	source.				



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Test	Description	Pass/Fail	Date	Conclusion	Sign
Test 4A	Description Test the direction of the arrival to a moving sound source.	Pass/Fail Pass	Date 2023-11- 30	Conclusion The direction of arrival to a sound source (human voice) was tested on the angles 0, -30, -60 and -90 degrees. The sound source was in a standstill position in front of the user at 2 meters from the sound source for 30 sec- onds at each angle. A per- son that spoke freely acted as the sound source and no noise was present during the test. The person spoke and moved between the test an-	Sign AR, RO
4 P	Test the range to a moving	Pass	2023-11	gles during the test. The re- sult of the test can be seen in table 3.	AD
4 β	sound source.	rass	30	(human voice) was tested on the ranges 1,2,3,4 and 5 meters in front of the user at 0 degrees. The sound source (human voice) was in a standstill position for 20 seconds at each range. A person that spoke freely acted as the sound source and no noise was present during the test. The person spoke and moved between the test ranges during the test. The result of the test can be seen in table 4.	RO
5	Test the tracking of the direc- tion and position estimate of a moving sound source.	Not exe- cuted.		Not tested.	
6	Test 4 and 5 with mulit- ple sound sources simul- tanously.	Not exe- cuted.		Not tested.	

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Direction [degrees]	Mean [degrees]	Standard deviation [degrees]
0	2.1	2.17
-30	1.4	2.99
-60	7.0,	1.76
-90	3.8	5.72

Table 3: Test result of the direction of arrival to a sound source (human voice).

Range [m]	Mean estimation error [m]	Standard deviation [m]
1	0.76	0.41
2	1.33	0.49
3	1.08	0.49
4	0.77	0.05
5	-0.52	0.20

Table 4: Test result of the range to a sound source (human voice).

1.3 Noise reduction

Test	Description	Pass/Fail	Date	Conclusion	Sign
7	Test of monaural be	beam- Pass	2023-12-	Tested with one haring aid,	EW
	former.	with note	04	beamformer towards signal	
				and white noise in oppo-	
				site direction. SNR as ta-	
				ble Table 6. Note that the	
				global SNR is the one the	
				test shows is working. The	
				segmented mean SNR is re-	
				versed, which is odd.	
7A	Test of monaural be	beam- Pass	2023-12-	Tested with one haring aid,	EW
	former interferer.	with note	04	beamformer towards signal	
				and interferer in opposite di-	
				rection. SNR as table Ta-	
				ble 7. Note that the global	
				SNR is the one the test	
				shows is working. The seg-	
				mented mean SNR is re-	
				versed, which is odd.	
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Test	Description	Pass/Fail	Date	Conclusion	Sign
8	Test of binaural beamformer noise.	Pass	2023-11- 30	Tested with white noise at 60 degrees to the left of the sig- nal source. SNR as table Ta- ble 8. The SNR has signifi- cantly increased for the left ear especially.	EW
8A	Test of binaural beamformer interferer.	Pass	2023-11- 30	Tested with interferer 60 de- grees to the left of the sig- nal source. SNR as table Ta- ble 9. The SNR has signifi- cantly increased for the left ear especially.	EW
9	Test of amplification differ- ence for two voices.	Pass	2023-11- 30	Tested by playing the same signal twice, ones the beam- former pointing to signal, ones pointing straight to the right and calculating SNS (Signal to Signal ratio). Re- sults in Table 10. Shows clearly how the beamformer pointed away from signal suppresses it greatly.	EW
10	Test of speech recognition in noisy environment.	Pass	2023-11- 30	Tested by placing one sound source playing a speech and white noise at the same time. SNR can be seen in Table 11	EW
11	Test of band-pass filter.	Not exe- cuted		Not tested	
12	Test of PTA amplification.	Not exe- cuted		Not tested	
13	Test of compression filter.	Not exe- cuted		Not tested	

	SNR _{seg,front}	SNR _{glob,front}	SNR _{seg,back}	SNR _{glob,back}
Before	1.4 dB	2.5 dB	1.2 dB	2.1 dB
After	-0.1 dB	3.3 dB	-0.1 dB	3.3 dB

Table 6: SNR test, monaural, segmented mean and global of noise test for beamformer

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	SNR _{seg,front}	SNR _{glob,front}	SNR _{seg,back}	SNR _{glob,back}
Before	-3.3 dB	-1.63 dB	-3.6 dB	-2.0 dB
After	-4.5 dB	-0.9 dB	-4.5 dB	-0.9 dB

 Table 7: SNR test, monaural, segmented mean and global of interferer test for beamformer

	SNR _{seg,left}	SNR _{glob,left}	SNR _{seg,right}	SNR _{glob,right}
Before	1.7 dB	2.8 dB	4.7 dB	7.1 dB
After	2.1 dB	6.9 dB	2.1 dB	6.9 dB

Table 8: SNR test, binaural, segmented mean and global of noise test for beamformer

	SNR _{seg,left}	SNR _{glob,left}	SNR _{seg,right}	SNR _{glob,right}
Before	-2.3 dB	-1.3 dB	-0.2 dB	2.3 dB
After	0 dB	5.5 dB	0 dB	5.6 dB

Table 9: SNR test, binaural, segmented mean and global of interferer test for beamformer

	SNS _{left}	SNS _{right}
Before	-1.61 dB	-0.9 dB
After	9.0 dB	9.0 dB

Table 10: SNR test, binaural, pointing the beamformer at or away from signal

	SNR _{seg,left}	SNR _{glob,left}	SNR _{seg,right}	SNR _{glob,right}
Before	1.8 dB	2.9 dB	5.1 dB	7.8 dB
After	3.0 dB	9.0 dB	3.0 dB	9.0 dB

 Table 11: SNR test, segmented mean and global for speech recognition and noise reduction.

2 G3

2.1 Face detection and tracking

Test	Description	Pass/Fail	Date	Conclusion	Sign
14	Test of face detection and tracking.	Partial pass	2023-12- 04	Face detected and tracked correctly. However, due to hardware malfunctioning the test was only performed on one face instead of 3 dif- ferent faces.	ME
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Test Protoc	ol



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Test	Description	Pass/Fail	Date	Conclusion	Sign
15	Test of detection of faces.	-	-	The requirement connected to this test was renegotiated. The test was therefore not preformed.	-
16	Test of tracking faces with user orientation change.	-	-	This test was never con- ducted due to hardware mal- functioning.	-
17	Test of tracking multiple faces.	-	-	This test was never con- ducted due to time con- straints.	-
18	Test of tracking multiple faces.	-	-	This test was never con- ducted due to time con- straints.	-

2.2 Depth estimation

Test	Description	Pass/Fail	Date	Conclusion	Sign
19	Test of depth estimation of a face.	Pass with note	2023-12- 04	From the five images the face was estimated with an absolute value of the error to be less than 30 % of ground truth depth making the test successful.	ME
20	Test non-existent.				

2.3 Eye-tracking



Test	Description	Pass/Fail	Date	Conclusion	Sign
21	Test of gaze association with video. The user looked at a face moving in the field of view. The 2D gaze was then plotted on the video from the scene camera.	Pass	2023-12- 04	The plotted 2D gaze was on the face.	ME
22	Test of 3D gaze estimation. The user was to focus their gaze on a moving face.	Partial pass	2023-12- 04	The horizontal and vertical angle was estimated within 10 degrees of the true angle of the face. The depth esti- mation of the gaze point was extremely bad and was fre- quently estimated to be more than 10 meters away from the true gaze point.	ME

2.4 Orientation

Test	Description	Pass/Fail	Date	Conclusion	Sign
23	Test of the orientation an-	Pass	2023-12-	Yaw, pitch and roll angle	OR
	gles, yaw, pitch and roll.		06	were all within 20 degree er-	MA
	Tested by placing the G3			ror. Values for the covari-	
	glasses on the ground in an			ance matrix for the magne-	
	environment free from mate-			tometer vary from 1-10 de-	
	rials that could disturb the			pending om what environ-	
	magnetic field for 10 sec-			ment or if the hardware is	
	onds. Then the glasses were			warm enough.	
	randomly moved for 3 sec-				
	onds before being returned				
	to their original position.				
24	Test of the yaw orientation.	Pass	2023-12-	Yaw angle were within 20	OR
	Tested by holding the pitch		06	degree error at every 90° ro-	MA
	and roll constant, rotating			tation.	
	the head 90° in the horizon-				
	tal plane and then standing				
	still for 10 seconds. Iterated				
	three times.				



3 ENTIRE SYSTEM

3.1 Relative orientation

Test	Description	Pass/Fail	Date	Conclusion	Sign
25	Test of sensitivity of the beamforming with eye- tracker for different head shapes.	-	-	This test was never con- ducted due to time con- straints.	-
26	Test of sensitivity of the rela- tive head shape function for different head shapes.	-	-	This test was never con- ducted due to time con- straints.	-

3.2 Sound source tracking and amplification

Test	Description	Pass/Fail	Date	Conclusion	Sign
27	Test for being able to per- form sound source tracking with glasses and HA on recorded data.	-	-	This test was never con- ducted due to hardware mal- functioning.	-
28	Test for being able to per- form sound source tracking with glasses and HA on live data.	-	-	This test was never con- ducted due to hardware mal- functioning.	-
29	Test for static case of beam- forming and visually choos- ing the direction for beam- forming.	-	_	This test was never con- ducted due to hardware mal- functioning.	-
30	Test for static case of beam- forming and visually choos- ing the direction for beam- forming with SNR require- ment.	-	-	This test was never con- ducted due to hardware mal- functioning.	-
31	Test for static user and mov- ing sound source of beam- forming and constant gaze point.	-	-	This test was never con- ducted due to hardware mal- functioning.	-
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Test	Description	Pass/Fail	Date	Conclusion	Sign
32	Test for static user and mov-	-	-	This test was never con-	-
	ing sound source of beam-			ducted due to hardware mal-	
	forming and visually attend-			functioning.	
	ing to the sound source.				
33	Test for moving user and	-	-	This test was never con-	-
	two static sound source of			ducted due to hardware mal-	
	beamforming and visually			functioning.	
	attending to the sound				
	source.				
34	Test for moving user and one	-	-	This test was never con-	-
	static sound source of beam-			ducted due to hardware mal-	
	forming and visually attend-			functioning.	
	ing to the sound source.				
35	Test for user moving head	-	-	This test was never con-	-
	and moving sound source of			ducted due to hardware mal-	
	beamforming and constant			functioning.	
	gaze point.				
36	Test of track and camera	-	-	This test was never con-	-
	alignment.			ducted due to hardware mal-	
				functioning.	

4 UI

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Test	Description	Pass/Fail	Date	Conclusion	Sign
37	Test functionality of GUI	Pass with note	2023-12- 04	 No GUI was created, but functionality still exists. Turn on/off amplification, display/change amplification in soundmexpro for DOA, Maya44 soundcard driver for beamformer. Record sound in code by list for beamformer, soundmexpro for DOA. Replay saved .wav file 	EW
38	Test recording on G3	Pass	2023-12- 04	Recording easily done in UI (G3_terminal) for the glasses.	EW
39	Test the playback of record- ings	Pass with note	2023-12- 04	Post processing of record- ing is available for all mod- ules of G3 and hearing aid DOA. NOTE: Not available for beamformer or combina- tion of G3/HA as in real- time	EW

5 PERFORMANCE TESTS

Test	Description	Pass/Fail	Date	Conclusion	Sign
40	Test the delay for the hearing	Pass	2023-12-	Beamformer mean delay 5	EW
	aids		04	ms. + 12 ms for hardware	
				(soundcard, preamps etc.) =	
				17 ms delay.	
41	Test the frequency of hear-	Pass	2023-12-	44100 Hz without clipping	EW
	ing aids.		04	for beamformer.	
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Test	Description	Pass/Fail	Date	Conclusion	Sign
42	Test the frequency of G3.	Pass	2023-12-	Runs in real time which	EW
			04	means this test is fulfilled.	
				Camera is at 25 fps, this	
				seems to be the bottleneck	
				during processing.	